

# Motor Feedback Systems Type M 15

## for AC Synchronous & BLDC Motors



- Incremental + commutation
- Practically no speed limitation, since up to 12000 RPM
- Very good dynamic behaviour through low moment of inertia of rotor and its minimal influence on the motor
- Very good drive stiffness since no coupling is used
- Compact size
- Excellent price-performance ratio
- Increased temperature range, -40 to +120°C
- Incomparable shaft play tolerances (to 0.7 mm axial)
- Better frequency, 200 KHz
- Flexibility, since the user can integrate in all actual motor sizes
- Simple mounting and adjustment since encoders come aligned and gapped

### NUMBER OF PULSES

200, 400, 500, 1000, 1024;  
optional 4, 6 or 8 pole commutation signals

### TECHNICAL DATA mechanical

Weight	23 g without cover, 28 g with cover
Dimensions	
Outside diameter	39.6 mm with cover, 37.1 mm without cover
Depth	27.9 mm with cover <sup>1</sup> , 24.1 mm without cover
Hub shaft diameters	6 mm / 8 mm / 10 mm / 3.18 mm (1/8") / 4.76 mm (3/16") / 6.35 mm (1/4") / 9.52 mm (3/8")
Hollow shaft tolerance	+0.026 mm ... -0.000 mm
Mating shaft length	min. 12 mm max. 22 mm with closed cover
Shaft misalignment	axial endplay <sup>2</sup> : +0.38 mm ... -0.38 mm radial runout: 0.05 mm (incl. angular misalignment)
Alignment of encoder channels to motor windings	coarse alignment: index mark on hub fine alignment: ±15° mechanical alignment range
Max. speed	12000 min <sup>-1</sup>
Moment of inertia	4.7 gcm <sup>2</sup>
Protection class (EN 60529)	IP40 <sup>4</sup> (version cable) IP30 <sup>4</sup> (version dual row connector)
Operating temperature	-40 ... +120 °C
Storage temperature	-40 ... +85 °C
Vibration resistance (IEC 68-2-6)	25 m/s <sup>2</sup> (5 ... 2000 Hz)
Shock resistance (IEC 68-2-27)	500 m/s <sup>2</sup> (11 ms)
Connection	shielded cable radial or dual row connector <sup>3</sup>
Housing	glassfibre reinforced plastic

<sup>1</sup> for radial cable connection

<sup>2</sup> + means away from mounting face

<sup>3</sup> 10 pins for version incremental only, 14 pins for version incremental+commutation

<sup>4</sup> mounted and with cover

for AC Synchronous & BLDC Motors

TECHNICAL DATA  
electrical

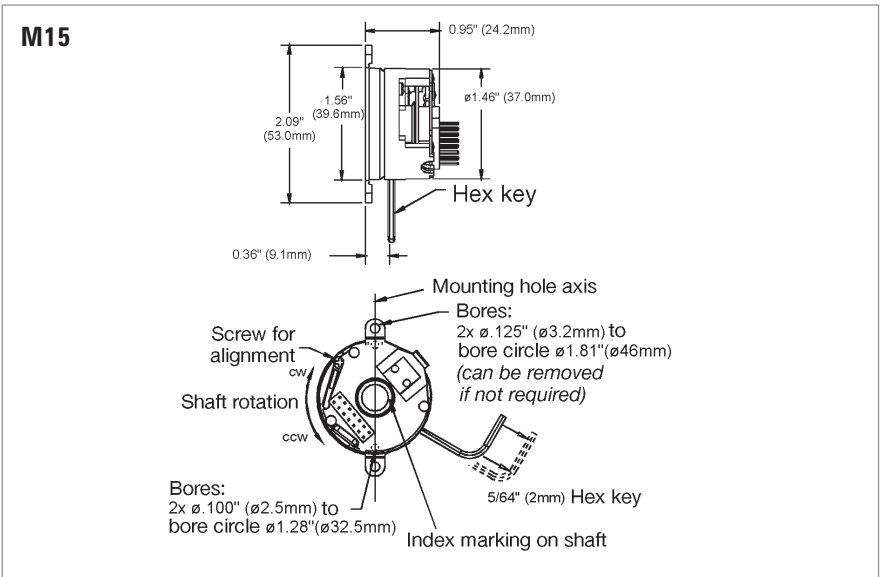
General design	as per DIN EN 61010-Teil 1, protection class III, contamination level 2, over voltage class II	
Supply voltage	DC 5 or 12 V ±10 % (SELV)	
Max. current w/o load	Incremental: max. 100 mA Incremental + Commutation: max. 120 mA	
Recommended external fuse	T 0.125 A	
Output circuit	NPN-Open Collector, max. 16 mA, Pull-up 2.0 KΩ RS 422, max. 40 mA	
Output signals		
Incremental	NPN-O.C: A, B, N	RS 422: A, B, N, $\bar{A}$ , $\bar{B}$ , $\bar{N}$
Commutation (optional):	NPN-O.C: U, V, W	RS 422: U, V, W, $\bar{U}$ , $\bar{V}$ , $\bar{W}$
Accuracy		
Incremental signals	max. ±5 arc-mins. (edge to any edge)	
Commutation signals	max. ±6 arc-mins.	
Phasing		
Incremental signals (A to B)	90° ±18° electrical	
Commutation signals	8 pole: 30°, 6 pole: 40°, 4 pole: 60° mechanical	
Index to U	±1° mech. index pulse center to U channel edge	
Pulse width		
Incremental signals	180° ±18° electrical	
Commutation signals	8 pole: 45°, 6 pole: 60°, 4 pole: 90° mechanical	
Max. output frequency	200 kHz	
Noise immunity <sup>1</sup>	as per EN 61000-4- 2, 3, 4, 8 EN 61000-4- 6 with 3 V/m	
Noise emission <sup>1</sup>	as per EN 50081-2 (1993 edition)	

<sup>1</sup> EMC values are only valid for version with screened cable (connection code A ... H)

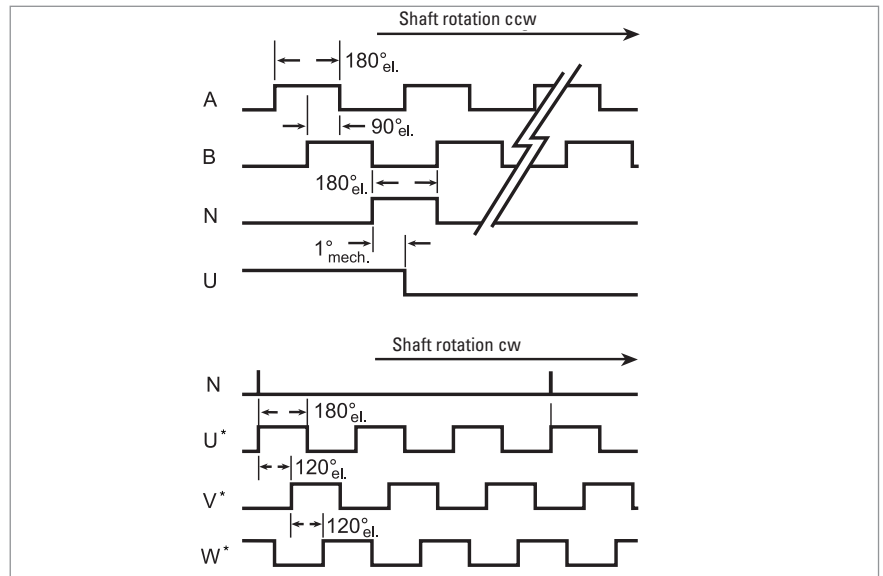
# Motor Feedback Systems Type M 15

## for AC Synchronous & BLDC Motors

### DIMENSIONAL DRAWINGS



### PULSE DIAGRAM



\* Example with 6 pole commutation

## for AC Synchronous & BLDC Motors

### CONNECTION DIAGRAM CABLE

Function	Colour for version incremental only, Code Electrical = 0, 1, 3	Colour for version incremental + commutation, Code Electrical = 6, 7, 9
$V_{CC\ com}^1$		red/white <sup>3</sup>
$V_{CC\ inc}^1$	red	red
GND inc	black	black
GND com		black/white <sup>3</sup>
$\bar{A}^2$	red/black	blue/black
A	green	blue
$\bar{B}^2$	white/black	green/black
B	orange	green
$\bar{N}^2$	blue	violet/black
N	white	violet
$\bar{U}^2$		brown/black
U		brown
$\bar{V}^2$		grey/black
V		grey
$\bar{W}^2$		white/black
W		white

<sup>1</sup>  $V_{CC\ com}$  resp.  $V_{CC\ inc}$  = + DC 5 V or + DC 12 V (see ordering data electrical)

<sup>2</sup> only with Output<sub>inc/com</sub> = RS 422

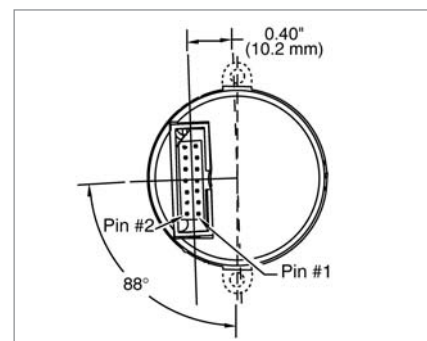
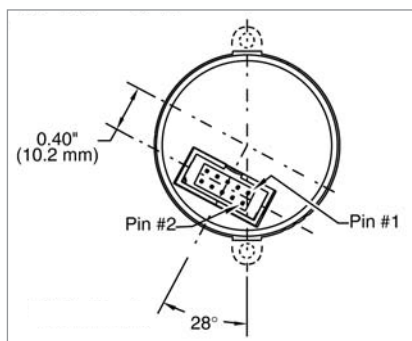
<sup>3</sup> not connected for code 6 and 9, as here  $U_{inc} = U_{com}$

### CONNECTION DIAGRAM DUAL ROW CONNECTOR

Pin	10 pole only incr., NPN-O.C., Code Electr. = 0, 1	10 pole only incr., RS422, Code Electr. = 3	14 pole incr. + commutation, Code Electr. = 6, 7, 9
1	A		$V_{CC}$
2	$V_{CC}$	$V_{CC}$	U
3	GND	GND	$\bar{U}$
4			V
5		$\bar{A}$	$\bar{V}$
6		A	W
7		$\bar{B}$	$\bar{W}$
8	B	B	$\bar{A}$
9		$\bar{N}$	A
10	N	N	B
11			$\bar{B}$
12			N
13			GND
14			$\bar{N}$

#### Pin Numbering:

For dual row connector with ribbon cable:  
The cable side marked red designates pin 1



# Motor Feedback Systems Type M 15

## for AC Synchronous & BLDC Motors

### ORDERING INFORMATION

Type	Pulses ppr incremental <sup>2</sup>	Poles commutation <sup>2</sup>	Housing	Electrical <sup>1</sup>	Hub diameter <sup>2</sup>	Connection
□	□ /	□ -	□	□	□	□
<b>M15-</b>	<b>0200</b> <b>0400</b> <b>0500</b> <b>1000</b> <b>1024</b>	<b>0</b> without <b>4</b> 4 pole <b>6</b> 6 pole <b>8</b> 8 pole	<b>0</b> without cover <b>1</b> closed cover for blind shaft <b>2</b> cover with bore for through shaft	<b>incremental only</b> <b>without commutation</b> <b>0</b> $U_{inc}=DC\ 5\ V$ ; output <sub>inc</sub> =NPN-O.C. <b>1</b> $U_{inc}=DC\ 12\ V$ ; output <sub>inc</sub> =NPN-O.C. <b>3</b> $U_{inc}=DC\ 5\ V$ ; output <sub>inc</sub> =RS 422 <b>incremental plus</b> <b>commutation signals</b> <b>6</b> $U_{inc}=DC\ 5\ V$ ; output <sub>inc</sub> =RS 422, $U_{com}=DC\ 5\ V$ ; output <sub>com</sub> =NPN-O.C. <b>7</b> $U_{inc}=DC\ 5\ V$ ; output <sub>inc</sub> =RS 422, $U_{com}=DC\ 12\ V$ ; output <sub>com</sub> =NPN-O.C. <b>9</b> $U_{inc}=DC\ 5\ V$ ; output <sub>inc</sub> =RS 422, $U_{com}=DC\ 5\ V$ ; output <sub>com</sub> =RS 422	<b>0</b> 6.35 mm ( $\frac{1}{4}$ "") <b>1</b> 9.52 mm ( $\frac{3}{8}$ "") <b>4</b> 6 mm <b>5</b> 8 mm <b>6</b> 10 mm <b>8</b> 4.76 mm ( $\frac{3}{16}$ "") <b>9</b> 3.18 mm ( $\frac{1}{8}$ "")	<b>0</b> dual row connector <b>1...8</b> dual row connector with mating ribbon cable 1=30 cm, 2=60 cm, ... <b>A...H</b> screened cable radial, A=30 cm, B=60 cm, ...
<sup>1</sup> $U_{inc}$ : Supply voltage incremental, $U_{com}$ : Supply voltage commutation (only if commutation selected) <sup>2</sup> allowed combinations see available combinations (pulses/poles)						

### Available combinations (pulses/poles)

Pulses ppr	Number of poles			
	0	4	6	8
0200	X			
0400	X			
0500	X	X	X	X
1000	X	X	X	X
1024	X	X	X	X